## Rules of Engagement

## Kinematic Motion Problems

1. Draw a motion diagram
2. Draw Reference Frame
3. Label Positions A, B, etc
4. Find pos, vel, time for each position
5. Find equation \& solve

## Force Problems

1. Draw picture
2. Draw ref. Frame
3. Draw FBD
4. Redraw force diagram replacing the object by a dot.
5. Resolve all force into x and y components
6. Show $\sum \mathrm{F}_{\mathrm{x}}=\mathrm{ma}_{\mathrm{x}}$, and $\sum \mathrm{F}_{\mathrm{y}}=\mathrm{ma}_{\mathrm{y}}$
7. Solve for unknown

## Projectile Motion Problems

1. Draw picture
2. Draw ref. Frame
3. Mark on picture points A and B
4. Write down in neat column form values for position, velocity, acceleration and time in both x and y directions at both points A \& B..
5. Remember, $\mathrm{x}_{\mathrm{B}}=\mathrm{v}_{\mathrm{Ax}} \Delta \mathrm{t}+\mathrm{x}_{\mathrm{A}}$ because $\mathrm{a}_{\mathrm{x}}=0$
6. Remember, $\mathrm{y}_{\mathrm{B}}=-.5 \mathrm{~g} \Delta \mathrm{t}^{2}+\mathrm{v}_{\mathrm{Ay}} \Delta \mathrm{t}+\mathrm{y}_{\mathrm{A}}$ because the object is just a falling body in the vertical direction.
7. Solve for the required quantity.

## Momentum Problems

1. Draw 2 pictures --- before and after
2. Indicate system!!
3. Draw the reference frame
4. Indicate on picture initial and final values of momentum
5. Solve

## Work Problems

1. Draw figure
2. Circle the system
3. Draw ref. Frame and show 0 ref. Level
4. Draw bar chart
5. Write equations and solve

## Equilibrium Problems

1.Draw picture
2. Draw ref. Frame
3. Draw FBD
4. Resolve all force into x and y components
5. Show $\sum F_{x}=$ $\qquad$ $=0$,
and $\sum \mathrm{F}_{\mathrm{y}}=\square=0$
6. Choose a pivot point P
7. Show $\sum \mathrm{T}=$ $\qquad$ $=0$
8. Solve system of equations for unknowns

## Circular Motion Problems

1. Draw FBD with one axis in the radial direction.
2. Make TOWARD the center the positive direction.
3. Sum forces in radial direction equals $\mathrm{m}^{2} / \mathrm{r}$.
4. Solve for unknown

## Rotational Dynamics problems.

1. Draw a FBD.
2. $\operatorname{Set} \sum T=$ $\qquad$ $=I C$
3. $\operatorname{Set} \sum \mathrm{F}=$ $\qquad$ $=$ ma, keeping in mind that a is not always equal to $\sigma$, but may be $\pm \mathrm{r} \sigma$, depending upon the reference frame. And remember, if rotation is clockwise, $\alpha<0$ !
4. Solve for unknown.

## Buoyancy Problems

1. Draw a picture.
2. Remember $F_{B}=$ the weight of the fluid displaced.
3. $\sum \mathrm{F}_{\mathrm{x}}=$ $\qquad$ $=0$
4. Solve for x .
